

Vector Theory (E3)

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Abstract

A general purpose platform for economic analyses.

Outline

1. Infrastructure
2. Processes
3. Vectors

Appendix A: Accounting

- A1. Scale
- A2. Flux

Appendix B: Symmetry

- B1: Equivalence
- B2: Conservation

Note

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1. Infrastructure

Section 1: Composition

Let a factor be defined as a phenomenon with a set of quantitative attributes, \mathbf{a} , such that

$$\mathbf{a}_t = [a_{1t} \dots a_{zt}] \quad (1.1)$$

for $i = 1 \dots z$ attributes at time t .

Let an index be defined as a function of a subset of the quantitative attributes of a factor, such that

$$\mathbf{b}_t = f(\mathbf{a}_t) \quad (1.2)$$

where \mathbf{a}_t is a subset of \mathbf{a}_t .

Let infrastructure be defined as a set of factors.

Section 2: Structure

Let ζ be the identifier of the ζ th factor in an infrastructure, for $\zeta = 1 \dots Z$ factors.

Let an array be defined as a function that describes the position of a factor with respect to a reference point.

Given an appropriate set of reference points, the arrays for a set of factors can be used to construct a map of an infrastructure.

2. Processes

Section 1: Composition

Let a reactant be defined as a factor that undergoes a set of transitions.

Let a regulator be defined as a factor that moderates a set of aspects of a set of transitions, but is not a reactant.

Let an input be defined as a reactant or regulator.

Let a product be defined as a factor that is formed by a set of transitions.

Let a residual be defined as a reactant that is intact after a set of transitions.

Let an output be defined as a product or residual.

Let a resource be defined as an input or output.

Let a process be defined as a set of transitions.

Section 2: Structure

Let γ be the identifier of the γ th transition in a process, for $\gamma = 1 \dots \Gamma$ transitions.

Let $\text{co}(\gamma)$ be a progression to the γ th transition in a process.

Let $\text{au}(\gamma)$ be synchronization with the γ th transition in a process.

Let $\text{fb}(\gamma)$ be a regression to the γ th transition in a process.

Let a process descriptor be defined as an expression of the structure of a process, such that

$$\begin{aligned} d = [& 1, \text{co}(\gamma); \dots \\ & \Gamma, \text{fb}(\gamma)] \end{aligned} \quad (2.1)$$

Given the process descriptor for a process, a map of that process can be constructed.

3. Vectors

Section 1: Composition

Let a source be defined as a factor where a set of resources originates.

Let a field be defined as a factors where a set of resources is utilized.

Let a vector be defined as a set of sources and a subset of the corresponding set of fields.

Section 2: Structure

Let a vector descriptor be defined as an expression of the structure of a vector, such that

$$D = [(1,1), \text{co}(\gamma,\zeta); \dots \\ (\Gamma,Z), \text{fb}(\gamma,\zeta)] \quad (3.1)$$

where ζ is the factor where the γ th transition occurs, for $\zeta = 1 \dots Z$ and $\gamma = 1 \dots \Gamma$.

Given a set of vector descriptors, a sequence of maps of a vector can be constructed.

A1. Scale

Let α_t be defined as the $1 \times A$ matrix of the set of inputs for a process, such that

$$\alpha_t = [\alpha_{t1} \dots \alpha_{tA}] \quad (\text{a1.1})$$

Let δ_t be defined as the $A \times 1$ matrix of indexes that corresponds to α_t .

Let β_{t+n} be the $1 \times B$ matrix of outputs that corresponds to α_t , such that

$$\beta_{t+n} = [\beta_{t+n1} \dots \beta_{t+nB}] \quad (\text{a1.2})$$

Let ϵ_{t+n} be defined as the $B \times 1$ matrix of indexes that corresponds to β_{t+n} .

Let scale be defined as the relationship between a variable and the quantity of a resource.

Let input scale be defined as the relationship between α_t and δ_t , such that

$$\delta_t = f(\alpha_t) \quad (\text{a1.3})$$

Let conversion scale be defined as the relationship between α_t and β_{t+n} , such that

$$\beta_{t+n} = g(\alpha_t, t, n) \quad (\text{a1.4})$$

Let output scale be defined as the relationship between β_{t+n} and ϵ_{t+n} , such that

$$\epsilon_{t+n} = h(\beta_{t+n}) \quad (\text{a1.5})$$

A2. Flux

Let π_{t+n} be defined as the net result of a process, such that

$$\pi_{t+n} = \beta_{t+n}\epsilon_{t+n} - \alpha_t\delta_t \quad (\text{a2.1})$$

Accounting for scale,

$$\begin{aligned} \pi_{t+n} &= g(\alpha_t, t, n)h(\beta_{t+n}) - \alpha_t f(\alpha_t) \\ &= g(\alpha_t, t, n)h(g(\alpha_t, t, n)) - \alpha_t f(\alpha_t) \end{aligned} \quad (\text{a2.2})$$

Let flux be defined as the relationship between π_{t+n} and a variable.

Let alpha-flux be defined as the relationship between π_t and α_t , such that

$$d\pi_t/d\alpha_t = g'(\alpha_t, t, n)h(g'(\alpha_t, t, n)) - f'(\alpha_t) \quad (\text{a2.3})$$

Let delta-flux be defined as the relationship between π_{t+n} and δ_t , such that

$$d\pi_t/d\delta_t = -\alpha_t \quad (\text{a2.4})$$

Let beta-flux be defined as the relationship between π_t and β_{t+n} , such that

$$d\pi_t/d\beta_{t+n} = \epsilon_t \quad (\text{a2.5})$$

Let epsilon-flux be defined as the relationship between π_t and ϵ_{t+n} , such that

$$d\pi_t/d\epsilon_{t+n} = \beta_{t+n} \quad (\text{a2.6})$$

B1: Equivalence

Principle of Equivalence:

the classification of a factor in a process is determined by the vector the process is categorized in.

Let π_{st+n} be defined as the standard form of π for a process with respect to a given vector, such that

$$\pi_{st+n} = \beta_{t+n}\epsilon_{t+n} - \alpha_t\delta_t \quad (\text{b1.1})$$

Let π_{rt+n} be defined as the reverse form of π_{st+n} , such that

$$\pi_{rt+n} = \alpha_t\delta_t - \beta_{t+n}\epsilon_{t+n} \quad (\text{b1.2})$$

Given these definitions,

$$\pi_{st+n} = -\pi_{rt+n} \quad (\text{b1.3})$$

or

$$\pi_{st+n} + \pi_{rt+n} = 0 \quad (\text{b1.4})$$

B2: Conservation

Principle of Conservation:

for any given process, all of the factors in a set of inputs must be accounted for in the set of outputs, and the set of inputs must account for the set of outputs.

Given this definition,

$$\pi_{t+n} = 0$$

(b2.1)

for all processes.

If selected inputs or outputs are excluded from the calculation of π , then π can have a nonzero value.

Let π_{t+n} be defined as a modified form of π_{t+n} where a subset of inputs is excluded from α_t .

Let π_{t+n} be defined as a modified form of π_{t+n} where a subset of outputs is excluded from β_{t+n} .

Let π_{t+n} be defined as a modified form of π_{t+n} where a subset of inputs and outputs are excluded from α_t and β_{t+n} , respectively.