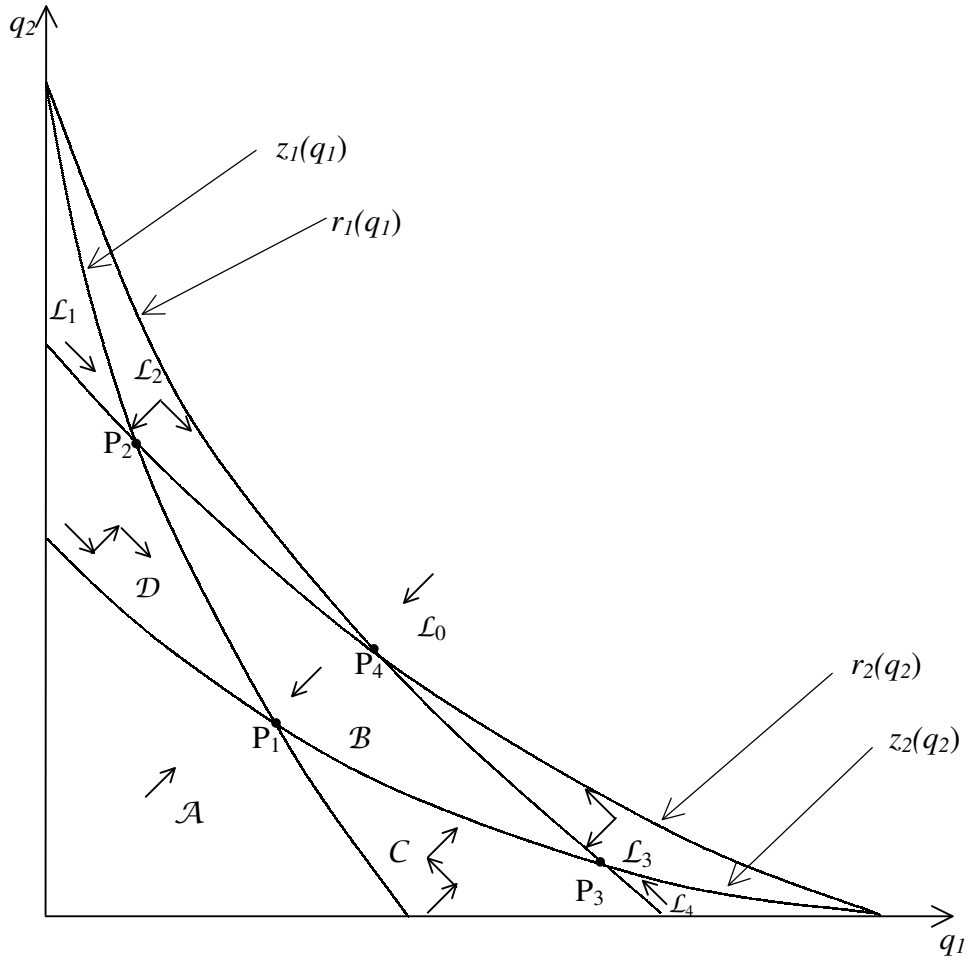
$q_2$
$z_1(q_1)$
$r_1(q_1)$
$\mathcal{L}_1$
$\mathcal{L}_2$
P2
$\mathcal{D}$
$\mathcal{L}_0$
P4
$r_2(q_2)$
$z_2(q_2)$
P1
$\mathcal{B}$
$\mathcal{A}$
$C$
$\mathcal{L}_3$
P3
$\mathcal{L}_4$
$q_1$