

Fair Bargains: Distributive Justice and Nash Bargaining Theory

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Abstract: the Suppes-Sen dominance relation is a weak and widely accepted criterion of distributive justice. We propose its application to Nash bargaining theory. The Nash Bargaining Solution (NBS) is characterised by replacing the controversial Independence of Irrelevant Alternatives axiom with an axiom embodying the Suppes-Sen principle. More precisely, maximality in the Suppes-Sen relation is shown to be *equivalent* to the NBS in the presence of Scale Covariance. The characterisation is far more robust than the standard one with respect to variations in the domain of bargaining problems. It is also shown that a subset of Nash's axioms imply the Suppes-Sen relation.

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1. Introduction

In the axiomatic theory of bargaining initiated by Nash (1950) one defines a set of admissible bargaining problems (e.g., convex problems) and imposes some desirable requirements (axioms) on the solution function, which picks an element from each problem; the aim is to characterise uniquely such a function. One interpretation of the axioms is as properties that should be satisfied by the choices of a *fair arbitrator* (e.g., Myerson (1990, p. 372-3), Young (1994, ch. 7), Mas Colell *et. al.* (1995, ch. 22.E) and, implicitly, Hammond (1991), p. 203). The axioms that characterise the Nash Bargaining Solution (NBS) include the powerful Independence of Irrelevant Alternative (IIA), which has been extensively discussed and criticised. Indeed, although IIA and its variations may be viewed as a relevant criterion of *rationality* for individual choice, it is difficult to see it as a compelling requirement of *fair arbitration*. As Binmore (1992, p.196) puts it:

“Some authors misunderstand Nash’s motives in formulating his bargaining solution and imagine that his axioms can be sensibly interpreted as criteria for a ‘fair arbitration scheme’ ... other axiom systems have been introduced to characterise other so-called ‘bargaining solutions’ that do make sense as fair arbitration schemes”.

We think that Binmore’s statement concerning Nash’s *axioms* is correct. In this paper we aim to show that -whatever Nash’s motives were- there are nonetheless very strong reasons to interpret Nash’s *solution* as an expression of fairness. We will illustrate a striking property of the NBS, which supports this interpretation and allows a characterisation that dispenses with IIA altogether. It turns out that the NBS is the only scale covariant bargaining solution satisfying the weak and widely accepted criterion of distributive justice known as *Suppes-Sen dominance* (Suppes (1966), Sen (1970), chs. 9 and 9*)^{1,2}.

¹ There are other modifications of Nash’s axioms concerning IIA. Lensberg (1988) replaces IIA with Stability, which applies when the number of players is a variable. In Mariotti (1994) IIA is relaxed to a weaker independence axiom, Independence of Revealed Irrelevant Alternatives. For comprehensive discussions of axiomatic bargaining theory see Roth (1979a), Thomson and Lensberg (1988), Peters (1992), Thomson (1995).

Given utility vectors x and y , x is said to Suppes-Sen dominate (SS-dominate) y if and only if there exists a permutation of x that Pareto dominates y . We refer to the application of this dominance criterion as the Suppes-Sen principle³. To see how weak the principle is, just note that, mathematically, SS-dominance coincides with first-order stochastic dominance. When applied to social welfare functionals, it does not discriminate almost at all; it is, rather, a ‘common denominator’. We quote from Sen (1970, p. 151):

“The conflicting claims of the maximin criterion and utilitarianism are difficult to resolve. Each has some attractive features and some unattractive ones. The [Suppes-Sen principle], when suitably constrained, seems to catch the most appealing common elements of the two. ... While it does not yield a complete social ordering, it does squeeze out as much juice as possible out of the use of “dominance” (or vector inequality), which is the common element in the maximin criterion, utilitarianism, and a number of other collective choice procedures involving interpersonal comparability”.

There are two main ideas behind the Suppes-Sen principle. First, ‘fair’ decisions should be, in some sense, *impersonal*: if x is considered ‘more just’ than y , this judgement should not depend on the position of any particular prespecified individual. In this respect, the principle appears to be a combination of Pareto optimality with Anonymity. Secondly, *ordinal interpersonal comparisons* of utility are meaningful (recall how, in social choice theory, Arrow’s (1951) impossibility theorem and in particular Sen’s (1970, p. 123-30) analogous result when *cardinal*

² Kolm (1971) uses the term “fundamental dominance”, Blackorby and Donaldson (1977) simply refer to “dominance”. The term ‘Suppes-Sen dominance’ seems to be due to Saposnik (1983) and is followed in more recent treatments such as Madden (1996).

³ Historical note: Suppes’ (1966) original definition of the Suppes-Sen principle was for the two-person case and, more importantly, involved no interpersonal comparison of utility. Sen (1970) showed that the principle as such was incompatible with Pareto optimality; thus he amended it to the current form using the so-called axiom of identity (whereby every agent i must have the same preferences of a different agent j when placing himself in j ’s position); and also generalised it to the n -person case.

intensities of preferences are available imply that utilities must satisfy some form of interpersonal comparability if reasonable and defined social choices are to be made). As far as we are aware, the relevance of the Suppes-Sen principle to Nash bargaining theory viewed as a theory of fair arbitration has not been studied. We propose to do so, as follows.

In Nash's bargaining theory a *disagreement point* is given, which is relevant for the outcome of the problem. On our interpretation, a bargaining problem is a special but important kind of social decision problem. A fair arbitrator who accepts ordinal interpersonal utility comparisons will want to apply the Suppes-Sen principle to the players' utilities *net* of the disagreement utility. It should be obvious from our earlier remarks about social welfare functions that even in bargaining theory one cannot travel very far on the basis of SS-dominance alone, when the class of scale-dependent solutions is considered. For example, both the Utilitarian (Myerson (1981)) and the Egalitarian (Kalai (1977)) bargaining solutions will yield SS-undominated outcomes for each problem. At first blush, it might appear that also all scale covariant solutions which satisfy the axioms of Pareto optimality and Anonymity (or Symmetry) will be bound to be compatible with the Suppes-Sen principle; one particularly obvious candidate being the *Kalai and Smorodinsky solution* (KSS), identified with *relative egalitarianism*. Surprisingly, this is not the case. Even more surprisingly, there exists only one scale-covariant solution which yields SS-undominated outcomes in each bargaining problem, and this is the NBS (Theorem 3.2).

The validity of the last assertion as a mere mathematical fact is not in doubt, but one important point of interpretation should be discussed. Scale covariant bargaining solutions are able to determine solution outcomes without the use of interpersonal utility comparisons of any sort. What is the meaning, then, of adopting a criterion that hinges on such interpersonal comparisons, albeit of an ordinal nature? Our methodological premise is that it is *logically meaningful* to compare utilities across individuals, but that it is *practically* difficult, if not impossible, to obtain

empirically the necessary scheme of interpersonal scaling⁴. We quote from Elster and Roemer (1991, p. 10-11):

“Let us assume that there is a *fact of the matter* in an interpersonal comparison of well-being ... It does not follow that we could ever discover it. Statements about the past pose similar problems. We tend to assume that there is a fact of the matter by virtue of which statements about the past are true if true, false if false. We may never be able to *establish* what the fact of the matter is -for example, whether it was raining when Caesar crossed the Rubicon. But that does not affect the *existence* of a fact of the matter. In one sense, other minds are just as inaccessible to us as the past. We need not entertain doubts about their existence and their essential similarity to our own, but we may despair at ever getting the details right”.

In other words, suppose that an arbitrator knew that the increase in utility that Mr. A derives when moving from a situation when he cannot play the trumpet to one where he can is twice as much as the increase in utility that Mr. B derives when moving from a situation when he cannot play the drums to one where he can. Then, the arbitrator should use this information to adjudicate how much each is allowed to play (and disturb the other). In practice, the arbitrator will *not* receive such detailed information, and will be forced to decide by avoiding interpersonal utility comparisons. However, if he believes in the Suppes-Sen principle of justice, he will wish to decide in such a way that, *if* given the extra information, he would not be found in violation of the principle. In this sense is the NBS the only means to reconcile the two desiderata.

⁴ Even Jevon’s (1871) famous anti-interpersonal comparisons dictum that “every mind is inscrutable to every other mind” seems to allow an interpretation in this direction. Indeed, he explicitly admits that “The susceptibility of one mind may ... be a thousand times greater than that of another”, thus giving *logical status* to interpersonal utility ratios (the position of Lionel Robbins (1932, 1938), often associated with Jevons, could be more uncompromising, if it derives, as is often argued, from logical positivism, which treats ethical statements as logically meaningless utterances). More recently, Hammond (1991) also doubts the possibility of an empirical derivation of interpersonally comparable utilities, while supporting their use in social decision making. See also the other essays in Elster and Roemer (1991), in particular Weymark (1991).

Beside yielding a novel characterisation of the NBS which dispenses with one of the controversial axioms in Nash's system, our approach has the added benefit of being robust, in various senses. First, it is robust to the choice of *domain* of the solution function. Nash (1950) confined himself to the class of convex problems; his axioms are not consistent on a wider domain⁵. Our characterisation, on the contrary, is robust to different -and, one could argue, more realistic- specifications of the domain (Theorem 4.2). This, we also argue, makes bargaining problems more directly comparable to standard social decision problems. In addition, the characterisation is showed to be robust to modifications of the axioms which could sensibly be required: (Corollary 3.3 and Theorem 5.2.1).

Finally, we also study a converse problem. Can an arbitrator who is, in some sense, *rational* be deemed to be also *fair* in the sense that he abides by the Suppes-Sen principle? We give a qualified positive answer, which depends on interpreting IIA and Pareto optimality as principles of rationality, and Symmetry as an informational constraint. We show that, on the domains of convex comprehensive or just comprehensive problems, in the presence of Symmetry, Pareto optimality and IIA imply that the choice must be SS-undominated (Theorem 5.2.1). In other words, an arbitrator who is rational in the sense specified above *must* behave as if he was taking into account the interpersonal ordinal utility comparisons implied by the Suppes-Sen principle. When the domain includes nonconvex problems, the same axioms yield in fact an even stronger property, namely full cardinal interpersonal comparability in the guise of Egalitarianism (Theorem 5.2.2).

2. Generalities

In Nash's (1950) theory, an n-person bargaining problem is a pair (S,d) , where $S \subseteq \mathfrak{R}^n$ and $d \in S$. The interpretation is that S is the set of *feasible utilities* attainable by the players and d is the *disagreement point* which results if no agreement is attained. In order to enhance expositional clarity, in the main text we make two simplifications:

⁵ A formal example is given in Mariotti (1996a).

$$(1) \quad n = 2;$$

$$(2) \quad d = \mathbf{0} \equiv (0,0).$$

None of the results depends on (1). In the appendix we show in full how some definitions and the main result generalise. As will be apparent, nothing conceptual is lost by assuming (1) but much is gained in readability. As for (2), this is a much used convention which saves on notation and is also immaterial, provided that the assumption of Scale Covariance made below is transformed to include, as usual, the weak requirement of *translation covariance*⁶.

This allows us to describe a bargaining problem simply as a set $S \subseteq \mathfrak{R}^2$. Let Π be a collection of bargaining problems. Then a *solution on Π* is a function $\varphi: \Pi \rightarrow \mathfrak{R}^2$ such that $\varphi(S) \in S$ for all $S \in \Pi$. It is standard to impose the following restrictions on S :

A1) S is compact;

A2) S is convex;

A3) there exists $s \in S$ such that $s > \mathbf{0}$ ⁷.

Restriction (A2) in particular is not trivial; we shall see later how one of the advantages of our approach is that it can be dispensed with, allowing one to consider nonconvex or even discrete sets of feasible alternatives. Let Γ denote the collection of all bargaining problems satisfying (A1) through (A3). Some standard properties that can be imposed on a solution are the following:

Weak Pareto Optimality (WPO): $s > \varphi(S) \Rightarrow s \notin S$.

Strong Individual Rationality (SIR): $\varphi(S) > \mathbf{0}$.

Covariance with Positive Scale Transformations (COV): let $\tau: \mathfrak{R}^2 \rightarrow \mathfrak{R}^2$ be a positive, linear, component by component transformation given by $\tau(x) =$

⁶ This requirement is satisfied by all the main solutions.

⁷ Vector inequalities: $x > y$ iff $x_i > y_i$ for $i = 1,2$.

$(\lambda_1 x_1, \lambda_2 x_2)$, with $\lambda_1, \lambda_2 > 0$, for all $x \in \mathfrak{R}^2$, and for any $X \subset \mathfrak{R}^2$ let $\tau(X) = \{y \in \mathfrak{R}^2 \mid y = \tau(x) \text{ for some } x \in X\}$. Then, $\varphi(\tau(S)) = \tau(\varphi(S))$.

Symmetry (SYM): suppose that $s \in S \Rightarrow (s_2, s_1) \in S$. Then, $\varphi_1(S) = \varphi_2(S)$.

Anonymity (AN): let $\pi: \mathfrak{R}^2 \rightarrow \mathfrak{R}^2$ be a map such that $\pi(x) = (x_2, x_1)$ for all $x \in \mathfrak{R}^2$. Then, $\varphi(\pi(S)) = \pi(\varphi(S))$.

Independence of Irrelevant Alternatives (IIA): $S \subseteq T$ and $\varphi(T) \in S \Rightarrow \varphi(T) = \varphi(S)$.

Some solutions that will be mentioned later are:

- The *Nash Bargaining Solution (NBS)* $v: \Gamma \rightarrow \mathfrak{R}^2$, defined by $v(S) \equiv \arg \max_{s \in S \cap \mathfrak{R}_+^2} s_1 s_2$.

For any $X \subseteq \mathfrak{R}^2$ let $\text{co}X$ denote the convex hull of X . For all $S \in \Gamma$, let $a_i(S) \equiv \max\{s_i \in \mathfrak{R} \mid s \in S, s \geq \mathbf{0}\}$. The point $a(S)$ is called the *ideal point*.

- The *Kalai and Smorodinsky Solution*⁸ (KSS) $\kappa: \Gamma \rightarrow \mathfrak{R}^2$, defined by $\kappa(S) \equiv \max\{s \in S \mid s \in \text{co}\{\mathbf{0}, a(S)\}\}$.

- The *Egalitarian Solution*⁹ (ES) $\eta: \Gamma \rightarrow \mathfrak{R}^2$, defined by $\eta(S) \equiv \max\{s \in S \mid s_1 = s_2\}$.

Nash (1950) proved that the NBS is the only solution on Γ that satisfies WPO, IIA, COV and SYM (or AN). We will refer to these four axioms as *Nash's axioms*. The KSS is sometimes identified with *relative egalitarianism* (see e.g. Moulin (1988)): it equalises the gains from the disagreement point of each player *relative* to the maximum possible such gain. It satisfies COV but not IIA. The ES simply equalises the gains from the disagreement point. It satisfies IIA but not COV, and hence it must be based on interpersonal (cardinal) utility comparisons, unlike the NBS

⁸ Kalai and Smorodinsky (1975).

⁹ Kalai (1975), Roth (1979b).

and the KSS which do not require any interpersonal comparisons. Note finally how all three solutions satisfy both SYM and AN.

3. Suppes-Sen Proofness

Given $s, t \in \mathfrak{R}^2$, s is said to *SS-dominate* t if $s > t$ or $(s_2, s_1) > t$. Suppose that it is logically meaningful (although not necessarily empirically possible) to make ordinal interpersonal comparisons of utility. Suppose that the utilities of the two players happen to be scaled with the same *unit*: in this case, *whether or not* the arbitrator has used such comparisons to determine a certain outcome, if that outcome is SS-dominated it can be reasonably argued to be unfair. If the arbitrator does not know whether the utilities are scaled with the same unit, he cannot know if he has been unfair or not, *unless* he chooses in such a way that, whatever the scaling, the outcome is not SS-dominated. This leads to the formulation of the following requirement for a solution function:

Suppes-Sen Proofness (SSP): $(s_2, s_1) > \varphi(S)$ or $s > \varphi(S) \Rightarrow s \notin S$.

Clearly, SSP is a strengthening of WPO obtained by combining an ‘anonymity’ principle with the optimality principle. However, it goes far beyond the mere joining of the axioms of WPO and AN (or SYM)! As we noted before, all three solutions NBS, ES and KSS satisfy both WPO and AN. Full egalitarianism, as embodied by the ES, clearly also satisfies SSP. But relative egalitarianism, as embodied by the KSS, does not.

Example 3.1: $S = \text{co}\{\mathbf{0}, (0,1), (5/8,1), (9/8,0)\}$. We have $\kappa(S) = (81/104, 9/13)$. Let $s = (29/40, 4/5)$. Then, since it is $s \in S$, $4/5 > 81/104$ and $29/40 > 9/13$, $\kappa(S)$ is SS-dominated (see Figure 1).

FIGURE 1 ABOUT HERE

On the other hand, COV excludes the ES. This already shows how powerful SSP becomes when paired with COV. More in general, we have the following main result:

Theorem 3.2: a solution $\varphi: \Gamma \rightarrow \mathfrak{R}^2$ satisfies COV and SSP if and only if $\varphi = v$.

Proof: given $S \in \Gamma$, suppose that there existed $s \in S$ with $(s_2, s_1) > v(S)$. Then also $s_1 s_2 > v_1(S) v_2(S)$, a contradiction. This, together with the well-known facts that the NBS satisfies COV and WPO, proves the ‘if’ part of the statement.

For the ‘only if’ part, let $S \in \Gamma$ and suppose by contradiction that $s \equiv \varphi(S) \neq v(S)$. We will show that then there exists $T \in \Gamma$ such that $\varphi(T)$ is SS-dominated. If there exists $t \in S$ with $t > s$ we are done, so assume that s is weakly Pareto optimal. Distinguish three cases.

Case 1: $s > \mathbf{0}$. Given any point $x \in \mathfrak{R}_{++}^2$, let $H(x)$ denote the branch of the symmetric hyperbola going through x , that is, $H(x) = \{y \in \mathfrak{R}_{++}^2 \mid y_1 y_2 = x_1 x_2\}$. Clearly, there exists $t \in H(s)$ such that $v(S) > t$. Consider now a positive linear transformation τ defined by $\tau_1(s) = \tau_2(t)$ and $\tau_1(t) = \tau_2(s)$. Such a transformation is defined (not uniquely) by $\tau(x) = (\lambda_1 x_1, \lambda_2 x_2)$ for all $x \in \mathfrak{R}^2$ where: $\lambda_1, \lambda_2 > 0$, $\lambda_1 \lambda_2 = t_2 / s_1 = s_2 / t_1$. Since $s, t \in H(s)$, these equations have a solution.

Let $\tau(S) \equiv T$. We have $\tau(v(S)) > \tau(t) = (\tau_2(s), \tau_1(s))$. Therefore $\tau(s)$ is SS-dominated by $\tau(v(S))$ in T , and by SSP it must be $\tau(s) \neq \varphi(T)$. However, by COV it must be $\varphi(T) = \varphi(\tau(S)) = \tau(\varphi(S)) = \tau(s)$, a contradiction.

Case 2: $s_1 = 0$ (the case $s_2 = 0$ is treated analogously; note that it cannot be $s = \mathbf{0}$ if s is weakly Pareto optimal). Since $v(S) > \mathbf{0}$, there exists $\alpha > 0$ such that $(\alpha, 0) < v(S)$. Let $\lambda_2 > 0$ be such that $\lambda_2 s_2 = \alpha$. Define the transformation τ by $\tau(x) = (x_1, \lambda_2 x_2)$. Now the argument of the previous case applies to $\tau(S)$.

Case 3: $s_1 > 0$, $s_2 < 0$. Let $t \in \mathfrak{R}^2$, with $t_1 < 0$ and $t_2 > 0$, be such such that $s_1 s_2 = t_1 t_2$. In addition, it is clearly possible to choose such a large negative value for t_1 that $t < v(S)$. Again define $\lambda_1, \lambda_2 > 0$ and τ as in case 1 and argue analogously. \diamond

Thus, choosing in accordance with the NBS is the *only way* for an arbitrator who has no information on the relative scaling of the players’ cardinal utilities -that is, who only knows the *equivalence class* of cardinal utility functions- to make sure that no injustice is committed according to the Suppes-Sen principle.

In conclusion of this section, we note that the NBS satisfies a much stronger fairness criterion than SSP, related to second-order stochastic dominance (or Generalised Lorenz dominance)¹⁰. Given $s, t \in \mathfrak{R}^2$, s is said to *GL-dominate* t if there exists $\alpha \in [0,1]$ such that $(\alpha s_1 + (1-\alpha)s_2, (1-\alpha)s_1 + \alpha s_2) > t$. It is immediately verified that $\alpha = 0$ implies SS-dominance and that $\alpha = 1$ implies weak Pareto dominance (and hence SS-dominance).

Generalised Lorenz Proofness (GLP): $(\alpha s_1 + (1-\alpha)s_2, (1-\alpha)s_1 + \alpha s_2) > \varphi(S)$,
 $\alpha \in [0,1] \Rightarrow s \notin S$.

It is easy to verify that the NBS cannot yield a GL-dominated outcome. By definition, the feasible set S is bounded above at $v(S)$ by the symmetric hyperbola through $v(S)$, $H(v(s))$. The set of points $t = (\alpha v_1(S) + (1-\alpha)v_2(S), (1-\alpha)v_1(S) + \alpha v_2(S))$ with $\alpha \in [0,1]$ is the segment joining $v(S)$ and $(v_2(S), v_1(S))$. This segment - connecting a point of $H(v(s))$ with another point which, being symmetric to the first, is also on $H(v(s))$ - lies entirely above $H(v(s))$. Therefore for any point t that GL-dominates $v(S)$ it must be $t \notin S$. Thus:

Corollary 3.3: let $\varphi: \Gamma \rightarrow \mathfrak{R}^2$ be a solution satisfying COV and SSP. Then it also satisfies GLP.

Thus, the informational constraint given by COV and the merely ordinal criterion of fairness given by SSP force one to accept a substantially more stringent interpersonal comparability criterion: for, clearly, the concept of GL-domination requires full *cardinal* interpersonal comparability (see also Theorem 5.2.2 below).

4. Other Domains and Multisolutions

This section contains some remarks on how the characterisation result of the previous section depends on the nature of the domain. The assumption that S is convex is justified by the fact that alternatives are expressed in von Neumann-Morgenstern utilities and that lotteries are available. These two requirements,

¹⁰ We thank Herve Moulin for drawing attention to this point. The terminology follows Madden (1996) and Shorrocks (1983).

although fairly standard, are not always palatable. If players are not expected utility maximisers, or if in some underlying game in strategic form no correlating device is available, or simply if players are not willing or able to randomise at all, the feasible set will not be convex or even a continuum¹¹. In addition, as Moulin (1996, p. 126) observes, “It is hard to believe that our search for operational criteria of fairness should be confined to a convex world”.

Fortunately, the characterisation in terms of SSP given above is quite robust to variations of the basic setting. Since the set of maximisers of the Nash product is not necessarily a singleton when the domain is not convex, in this section we turn to *multisolutions*¹². Let Π be a collection of bargaining problems. Then a *multisolution on Π* is a correspondence $\varphi: \Pi \rightarrow \mathfrak{R}^2$ such that $\varphi(S) \subseteq S$ for all $S \in \Pi$. The NBS viewed as a multisolution is defined analogously to the solution; the KSS and the ES are always single-valued when they are well-defined. Some axioms are redefined accordingly; a star indicates that they refer to multisolutions:

Weak Pareto Optimality (WPO*): $s > t \in \varphi(S) \Rightarrow s \notin S$.

Strong Individual Rationality (SIR*): $s \in \varphi(S) \Rightarrow s > \mathbf{0}$.

Symmetry (SYM*): suppose that $s \in S \Rightarrow (s_2, s_1) \in S$. Then, $s \in \varphi(S) \Rightarrow (s_2, s_1) \in \varphi(S)$.

Independence of Irrelevant Alternatives (IIA*): $S \subseteq T$ and $\varphi(T) \cap S \neq \emptyset \Rightarrow \varphi(S) = \varphi(T) \cap S$.

Suppes-Sen Proofness (SSP*): $(s_2, s_1) > t \in \varphi(S)$ or $s > t \in \varphi(S) \Rightarrow s \notin S$.

COV and AN remain unchanged.

¹¹ After two crucial contributions by Kaneko (1980) and Herrero (1989) the convexity assumption has received much attention recently: see, e.g., Conley and Wilkey (1996), Mariotti (1996a) and Zhou (1996).

¹² Although some authors feel uneasy about the idea of bargaining multisolutions, they have been used in recent significant developments of bargaining theory: see Blackorby *et al.* (1994, 1996).

We consider two interesting domains. The first is Σ , the class of problems S that satisfy (A1) and (A3) in section 2 and such that, in addition, S is *comprehensive* ((A4) below):

A4) let $s \leq s' \leq s''$; then $s, s'' \in S \Rightarrow s' \in S$.

The second domain is Θ , the class of problems S that satisfy (A3) of section 2 and such that, in addition, S contains a *finite* number of alternatives. For comparison, we summarise next some results of Mariotti (1996a):

Theorem 4.1: there exists no solution $\varphi: \Sigma \rightarrow \mathfrak{R}^2$ that satisfies Nash's axioms. There exists however a multsolution $\varphi: \Sigma \cup \Theta \rightarrow \mathfrak{R}^2$ that satisfies WPO*, COV, SYM* and IIA*. This multsolution is unique and it is the NBS. Finally, the NBS is also the only multsolution $\varphi: \Theta \rightarrow \mathfrak{R}^2$ that satisfies these axioms.

Single-valuedness is thus incompatible with Nash's axioms. We also note that there exists no characterisation in terms of WPO*, COV, SYM* and IIA* for the NBS multsolution $\varphi: \Sigma \rightarrow \mathfrak{R}^2$ (Kaneko (1980) has a characterisation on this domain which involves also an upper-semicontinuity axiom). Σ is the natural domain to consider when randomisations are available but the players are not necessarily expected utility maximisers (Rubinstein *et al.* (1992)), or they cannot correlate their strategies in the underlying strategic form description. Θ is the natural domain to consider when randomisations are not available at all. In the present approach, we have:

Theorem 4.2: a multsolution $\varphi: \Pi \rightarrow \mathfrak{R}^2$, with $\Pi \in \{\Sigma, \Theta, \Sigma \cup \Theta\}$, satisfies COV and SSP* if and only if $\varphi \subseteq v$. In particular, there exist *solutions* $\varphi: \Pi \rightarrow \mathfrak{R}^2$, with $\Pi \in \{\Sigma, \Theta, \Sigma \cup \Theta\}$, which satisfy COV and SSP, and such solutions are all selections from the NBS.

Here, the notation $\varphi \subseteq v$ means: $\varphi(S) \subseteq v(S)$ for all $S \in \Pi$. The proof of this theorem uses the same argument used for theorem 3.1, so we will not repeat it here.

These results suggest that, unlike the standard characterisation, our new characterisation of the NBS is relatively independent of the precise structural properties of the feasible set in the domain (observe that Corollary 3.3 is equally robust to changes of domain). One of the main advantages of this feature is that it

makes bargaining problems more directly comparable to standard social decision problems, in the following sense. In the latter type problem one typically has (see e.g. Sen (1970)) a given set X of ‘physical’ alternatives, and individual preferences on X are then allowed to vary. In traditional bargaining theory, to the contrary, also the set X must be allowed to vary; otherwise, one might not be able to obtain in the feasible domain the problems needed for the proof (e.g., in Nash’s (1950) case, one needs a symmetric rectangle to apply IIA). Our characterisation overcomes this difficulty, because the *only* axiom which involves comparisons of different bargaining problems is COV: it is perfectly possible, then, to think of the set of physical alternatives as fixed¹³.

5. Remarks

5.1. Rational Fairness? Axiomatic Foundation of SSP

So far we have considered SSP as a basic fairness desideratum, and have shown that it can replace IIA, which is more appropriately considered as a *rationality* desideratum for individual choice behaviour, in Nash’s axiom system¹⁴. In this section we briefly consider a converse problem, and study to what extent IIA implies that choices must *implicitly* be based on the interpersonal utility comparisons embodied in the Suppes-Sen criterion, or even stronger ones. The results proved so far show that SSP follows from the four Nash’s axioms. On the other hand, IIA and WPO alone clearly do not imply SSP (for example, the solution that maximises the first player’s

¹³ The only additional structural requirement needed in the bargaining framework is, of course, the presence of a dominated alternative.

¹⁴ On Θ , IIA is easiest to interpret: classical results (Arrow (1959)) imply that imposing IIA on φ is equivalent to imposing the existence of a binary relation that φ maximises. On continuum domains, the situation is more complex (see e.g. Peters and Wakker (1991), Bossert (1994) and Sánchez-Antón (1996)). Also, recall our interpretation of the NBS as an *arbitrated* outcome. If it is seen, on the contrary, as the outcome of *strategic* bargaining, then even WPO is a dubious requirement (Fernandez and Glazer (1991), Haller and Holden (1991), Mariotti (1996b) and Ray and Vohra (1992) all show, in different models, how even in the presence of perfect and complete information agreements may be suboptimal).

utility in each problem satisfies IIA and WPO but not SSP). However, they do so in the presence of SYM, at least on the domains of convex comprehensive or just comprehensive problems. Let Γ^{com} denote the class of all problems satisfying (A1) through to (A4).

Theorem 5.1.1: let $\varphi: \Pi \rightarrow \mathfrak{R}^2$, with $\Pi \in \{\Gamma^{\text{com}}, \Sigma\}$, be a solution satisfying IIA, WPO and SYM. Then, it also satisfies SSP.

Proof: suppose not, and let $S \in \Gamma^{\text{com}}$ be a problem such that $s = \varphi(S)$ is SS-dominated. That is, there exists $t \in S$ with $t > s$ or $t > (s_2, s_1)$. Consider the latter case. Define $T = \text{co}\{\mathbf{0}, s, (s_2, s_1)\}$. By convexity and comprehensiveness, $T \subseteq S$, and by IIA $\varphi(T) = s$. Since T is symmetric, by SYM $s_1 = s_2$. Then $t > (s_2, s_1)$ implies $t > s$, contradicting WPO.

The proof for the case $S \in \Sigma$ proceeds analogously, by constructing T as the polygon of vertices $\mathbf{0}$, $(0, s_i)$, (s_j, s_i) , (s_j, s_j) , (s_i, s_j) and $(s_i, 0)$ where $i, j \in \{1, 2\}$ and $s_j \in \min\{s_1, s_2\}$. In this case $T \subseteq S$ by comprehensiveness alone. \diamond

We also report a result communicated to us by J. Greenberg (proof available upon request), which strengthens theorem 5.1.1 for the domain Σ and shows that in this case the arbitrator must *explicitly* make full cardinal interpersonal comparisons (recall that Corollary 3.3 required an *implicit* use of such comparisons, in the sense of respecting COV):

Theorem 5.1.2 (Greenberg): a solution $\varphi: \Sigma \rightarrow \mathfrak{R}^2$ satisfies IIA, WPO and SYM if and only if $\varphi = \eta$.

One interesting, if not compelling, key to read these results is to view SYM as an informational constraint, rather than as a fairness requirement. When the feasible set is symmetric, there is nothing on the basis of which the arbitrator can possibly differentiate between the players, if he decides on the basis of utility information alone. Under this interpretation, theorem 5.1 says that an arbitrator who is thus constrained and who is ‘rational’ in the sense of abiding by IIA and WPO is also necessarily ‘fair’ in the Suppes-Sen sense.

5.2. Weakening of the Axioms

It is evident from the proof of Theorem 3.2 that there is a great deal of freedom in the choice both of the point t and of the scale transformation τ . Accordingly, from the mathematical viewpoint, the theorem can be considerably strengthened. We note two such strengthenings which may be also conceptually relevant.

One potential objection to SSP is that, given a problem S and its solution $\varphi(S)$, the alternative $(\varphi_2(S), \varphi_1(S))$ may not be feasible. In this case it could be asked: why should the issue of Pareto domination of a non-feasible alternative be of any bearing for the issue of arriving at a fair decision *within* the feasible set? Nonfeasible alternatives should be, to all effects, irrelevant. In other words, one might want to weaken SSP to:

SSP:** $s > (\varphi_2(S), \varphi_1(S)) \in S$ or $s > \varphi(S) \Rightarrow s \notin S$.

However, replacing SSP with SSP** in the statement of Theorem 3.2 would not affect its validity. It is obvious, in fact, that one can choose for t the point of intersection between the segment joining $\mathbf{0}$ and $v(S)$ and the hyperbula on which s lies. Then, by convexity (or, in the nonconvex case, by comprehensiveness), $t \in S$. Summarising:

Theorem 5.2.1: a solution $\varphi: \Gamma \rightarrow \mathfrak{R}^2$ satisfies COV and SSP** if and only if $\varphi = v$.

Further, it has sometimes been argued that COV is not as innocent as it looks (e.g. Kalai (1985), Rubinstein *et al.* (1992)). In the proof of Theorem 3.2 the coefficients λ_1 and λ_2 were only determined up to their ratio (see the Appendix for the generalisation of this statement to general n -player problems). Consequently, the class of transformations for which COV should hold can be restricted, and a new interpretation can be offered. Suppose, in particular, that we required $\lambda_1 + \lambda_2 = 1$. Then, COV could have the following interpretation. Given a feasible set S , consider a situation where only one of the two players gets his part of the arbitrated alternative $\varphi(S)$, while the other gets nothing. In particular, with probability λ_1 only player 1 gets $\varphi_1(S)$, and with probability $(1-\lambda_1)$ only player 2 gets $\varphi_2(S)$. COV now requires that the

decision of the arbitrator should be the same in this situation and in the standard one where both players can be satisfied.

6. Conclusion

In this paper we have supported and characterised the NBS as an expression of distributive justice¹⁵. We emphasise in conclusion that this interpretation is only valid in circumstances when the axiomatic solution of a bargaining problem à la Nash can be held to be appropriate for issues of fairness. In particular:

i) there is one distinguished point (d) which is allowed to be relevant for solving the distributional problem;

ii) cardinal utility information is available;

iii) the decision can be made on the basis of utility information alone.

Sen (1970), for example, has discussed situations in which the disagreement point should have no bearing on justice issues (note, however, that the interpretation of d as disagreement point is not necessary; all that matters is that there exists a Pareto dominated point for which Arrow's Independence can be violated). If (ii) and (iii) are not good assumptions (e.g. Roemer (1986, 1990, 1996)), other methods and procedures for deciding fairly will be more useful (see e.g., Young (1994) and Brams and Taylor (1996)).

We believe that it is possible to justify (i), (ii) and (iii) in general, but in this paper we eschew a discussion which is more philosophical in nature. We make instead a minimal claim which should be uncontroversial: *there exist* situations where (i), (ii) and (iii) hold. For those cases, we hope to have shown that the NBS is the most

¹⁵ The mentioned characterisation of the NBS in terms of *Consistency* by Lensberg (1988) also lends support, from a different perspective, to this interpretation. See Young (1994, ch. 7) for a discussion of this interpretation, Krishna and Serrano (1996) for the relation with *strategic* bargaining, and Thomson (1990) for a general discussion of the Consistency principle. We should also mention the original approach by Gauthier: in Gauthier (1986) he claimed that the KSS is simultaneously an expression of rational bargaining *and* of fairness, but it appears from Gauthier and Sugden (1993) that he now views the NBS as a better candidate to perform that double role.

appropriate way of resolving conflicts of interest fairly, being the only solution that reconciles two powerful yet conflicting needs: on the one hand, interpersonal comparisons of utility should be not used *in its calculation*; on the other hand, basic principles of fairness relying on such comparisons should not be violated by *its outcomes*.

Appendix

All the definitions and arguments for the results of the text generalise easily to the n -person case. In this appendix, by way of illustration, the definitions of SSP and GLP and the proof of Theorem 3.2, which is the least straightforward to generalise, are given. The generalisations of domains, standard axioms and solutions are obvious. Given $s, t \in \mathfrak{R}^n$, s is said to *SS-dominate* t if $\mathbf{A}s > t$ for some permutation matrix \mathbf{A} ; s is said to *GL-dominate* t if $\mathbf{A}s > t$ for some bistochastic matrix \mathbf{A} .

Suppes-Sen Proofness (SSP): $\mathbf{A}s > \varphi(S)$ for some permutation matrix $\mathbf{A} \Rightarrow s \notin S$.

Generalised Lorenz Proofness (GLP): $\mathbf{A}s > \varphi(S)$ for some bistochastic matrix $\mathbf{A} \Rightarrow s \notin S$.

Theorem A.3.2: A solution $\varphi: \Gamma \rightarrow \mathfrak{R}^n$ satisfies COV and SSP if and only if $\varphi = v$.

Proof: ‘If’: We note a stronger property of v , namely that it satisfies GLP. That this is so follows from the fact that the Nash product is a symmetric increasing concave function and from standard characterisation results available in the literature¹⁶.

‘Only if’: let $S \in \Gamma$ and suppose by contradiction that $s \equiv \varphi(S) \neq v(S)$. We will show that then there exists $T \in \Gamma$ such that $\varphi(T)$ is SS-dominated. If there exists $t \in S$

¹⁶ The relevant result for our assertion is: s GL-dominates t if and only if $f(s) \geq f(t)$ for all increasing symmetric quasi-concave real-valued functions f , with strict inequality for some such f . See for instance Madden (1996, Theorem 2). For general surveys see Mosler (1994) and Moulin (1988), where the relationship with Shur-convexity is noted.

with $t > s$ we are done, so assume that s is weakly Pareto optimal (hence, in particular, not $s \leq \mathbf{0}$). Distinguish three cases.

Case 1: $s > \mathbf{0}$. Given any point $x \in \mathfrak{R}_{++}^n$, let $H(x)$ denote the symmetric hyperboloid going through x , that is, $H(x) = \{y \in \mathfrak{R}_{++}^n \mid \prod_i y_i = \prod_i x_i\}$. Clearly, there exists $t \in H(s)$ such that $v(S) > t$. In addition it is possible to choose t so that $t_i \neq s_i$ for all $i \in \{1, 2, \dots, n\}$. Consider now a positive linear transformation τ defined by $\tau(s) = \mathbf{A}t$, where \mathbf{A} is the $n \times n$ permutation matrix which moves the i^{th} component to the $(i+1)^{\text{th}}$ place (setting $n+1 = 1$). That is:

$$\mathbf{A} \equiv \begin{bmatrix} 0 & 0 & 0 & \dots & 0 & 1 \\ 1 & 0 & 0 & 0 & \dots & 0 \\ 0 & 1 & 0 & 0 & \dots & 0 \\ 0 & 0 & 1 & 0 & \dots & 0 \\ & & & \dots & & \\ 0 & 0 & \dots & 0 & 1 & 0 \end{bmatrix}$$

We show that such a transformation τ exists (not uniquely). Denote \mathbf{S} and \mathbf{T} the $n \times n$ diagonal matrices with the components of s and t , respectively, on their diagonal, and denote $\boldsymbol{\lambda}$ the $n \times 1$ vector of coefficients representing τ (that is, $\tau_i(x) \equiv \lambda_i x_i$ for all $x \in \mathfrak{R}^n$, $i \in \{1, 2, \dots, n\}$). It must be proved that the homogeneous system:

$$(A1) \quad \mathbf{S}\boldsymbol{\lambda} = \mathbf{A}\mathbf{T}\boldsymbol{\lambda}$$

has (a class of) strictly positive solutions in $\boldsymbol{\lambda}$. (A1) has nontrivial solutions if and only if:

$$(A2) \quad |\mathbf{S} - \mathbf{A}\mathbf{T}| = 0.$$

We have:

$$\mathbf{K} \equiv \mathbf{S} - \mathbf{A}\mathbf{T} = \begin{bmatrix} s_1 & 0 & 0 & \dots & 0 & -t_n \\ -t_1 & s_2 & 0 & 0 & \dots & 0 \\ 0 & -t_2 & s_3 & 0 & \dots & 0 \\ & & & \dots & & \\ 0 & \dots & 0 & -t_{n-2} & s_{n-1} & 0 \\ 0 & 0 & \dots & 0 & -t_{n-1} & s_n \end{bmatrix}$$

Expanding along the first row:

$$(A3) \quad |\mathbf{K}| = s_1|\mathbf{M}_{11}| + (-1)^{n+1}(-t_n)|\mathbf{M}_{1n}|,$$

where M_{ij} denotes the minor of \mathbf{K} obtained by removing the i^{th} row and j^{th} column. By the properties of triangular matrices (e.g. Birkhoff and MacLane (1953), p. 303), $|\mathbf{M}_{11}| = \prod_{i \neq 1} s_i$ and $|\mathbf{M}_{1n}| = \prod_{i \neq n} t_i$. Note that the second term on the RHS of (A3) is negative for all n . Therefore (A2) holds if and only if $\prod_i s_i = \prod_i t_i$ or, equivalently, if and only if $t \in H(s)$. Since t was chosen exactly in this way, (A1) has nontrivial solutions.

Suppose now that λ^* is a nontrivial solution of (A1) and that $\lambda^*_{i_1} < 0$ (resp. = 0) for some $i_1 \in \{1, 2, \dots, n\}$. This means (by inspection of \mathbf{K} and the fact that $s, t > \mathbf{0}$) that $\lambda^*_{i_1-1} < 0$ (resp. = 0). Consequently, $\lambda^*_{i_1} < 0$ (resp. = 0) for *all* $i \in \{1, 2, \dots, n\}$. The case $\lambda^* = \mathbf{0}$ is excluded by nontriviality. If $\lambda^* < \mathbf{0}$, then $-\lambda^* > \mathbf{0}$ is also a solution. We conclude that the desired τ exists in this case.

Now let $\tau(S) \equiv T$. We have $\tau(v(S)) > \tau(t) = \mathbf{A}^{-1}\tau(s)$. Therefore $\mathbf{A}\tau(v(S)) > \tau(s)$, and by SSP it must be $\varphi(T) \neq \tau(s)$. However, by COV it must be $\varphi(T) = \varphi(\tau(S)) = \tau(\varphi(S)) = \tau(s)$, a contradiction.

Case 2: There exists $I \subset \{1, 2, \dots, n\}$ with $s_i = 0$ for $i \in I$ and $s_i > 0$ for $i \in \{1, 2, \dots, n\} \setminus I$. Without loss of generality, write s (possibly relabeling the axes) in such a way that the first k components are positive and the other negative: that is, let k be such that $s_i > 0$ for $1 \leq i \leq k$ and $s_i = 0$ for $k < i \leq n$. Now let $t \in \mathfrak{R}^n$ have components with signs as follows : $t_i > 0$ for $1 \leq i < k$ and $i = n$; $t_i = 0$ for $k \leq i < n$. In addition, let $t < v(S)$ (this is possible since $v(S) > \mathbf{0}$). Define the system (A1) as in case 1. The matrix \mathbf{K} now has one or more rows whose entries are all zero (certainly the last row, since $t_{n-1} = s_n = 0$), therefore (A1) has nontrivial solutions. If λ^* is a nontrivial solution, by the choice of sign of t we now have that $\lambda_{i-1} \setminus \lambda_i = s_i \setminus t_{i-1}$ whenever $s_i > 0$ (and hence $t_{i-1} > 0$)¹⁷. Therefore the $\lambda^*_{i_1}$ have all the same sign for $1 \leq i \leq k$. Since the

¹⁷ Setting $1 - 1 \equiv n$.

other λ^*_i , $k < i \leq n$, are all free variables, the choice $\lambda^* > \mathbf{0}$ is certainly allowed, and the proof for this case concludes as in case 1.

Case 3: There exists $I \subset \{1, 2, \dots, n\}$ with $s_i < 0$ for $i \in I$ and $s_i > 0$ for $i \in \{1, 2, \dots, n\} \setminus I$. Without loss of generality, let k be such that $s_i > 0$ for $1 \leq i \leq k$ and $s_i < 0$ for $k < i \leq n$. Define $s' \equiv (s_1, s_2, \dots, s_{k-1}, -s_k, -s_{k+1}, \dots, -s_{n-1}, s_n)$. Let $t \in \mathfrak{R}^n$ have the following properties:

- (a) $\text{sign } t_i = \text{sign } s'_i$;
- (b) $\prod_i s'_i = \prod_i t_i$;
- (c) $t < v(S)$.

Given (b), (c) is possible by making the negative components of t sufficiently large in absolute value. At this point the argument proceeds in a way analogous to case 1 and will not be repeated. \diamond

Observation: By reduction (using induction) to echelon form of \mathbf{K} it is easy to see that in fact the null-space of \mathbf{K} in case 1 has dimension 1 for all n . The transformation τ is therefore subject to exactly the same degree of freedom as in the two-person case, and the observations about the role of COV made in section 5.2.2 for that case apply here as well.

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